

# A Power Quality Improved by using Fuzzy Logic Controller in Bridgeless Converter Based Computer Power Supply

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## ABSTRACT

In this paper Poor power quality, direct dynamic response, high contraction extend, consonant rich, incidentally thick, peaky, significant issues current are the huge issues which are sometimes experienced in conventional Switched Mode Power supplies (SMPSs) used as a piece of PCs. To diminish these issues, it is proposed here to use a non-separated bridgeless buck-support single-ended primary-inductor converter (SEPIC) in discontinuous conduction mode (DCM) at the front end of a SMPS. The bridgeless SEPIC at the front end gives unequivocally controlled output dc voltage even under progressive data voltage and load varieties. The output of the front end converter is associated with a half system dc-dc converter for withdrawal and besides to acquire particular dc voltage levels at the load end that are required in a PC. Controlling a lone output voltage can coordinate the different dc output voltages also.

**Keywords:** Bridgeless converter; PFC; input current; computer power supply; power quality

## I. INTRODUCTION

In many electronic apparatuses controlled up from the utility, use the established strategy for air conditioning dc amendment which includes a diode bridge rectifier (DBR) trailed by a huge electrolytic capacitor. The uncontrolled charging and releasing of this capacitor actuates consonant rich current being drawn from the utility which conflicts with the universal power quality standard cutoff points [1-2]. Present day air conditioning dc converters consolidate control consider redress (PFC) and consonant current decrease at the purpose of regular coupling (PCC) which enhances voltage direction and productivity [3-5] at the load end. (PC) is one of the electronic gear which is seriously powered by power quality issues. Single stage and two phase transformations of air conditioning voltage into dc voltage have been utilized as a part of PCs to keep up consonant substance inside cutoff points and furthermore to get solidly managed various outputs. Single stage power transformation is basic, smaller and savvy. Be that as it may, it experiences poor dynamic reaction, control multifaceted nature, high capacitance esteem and high segment push. In this

way, two phase change of air conditioning voltage into different dc voltages is for the most part favored in PCs [6]. The segment tally in a two phase control supply is significantly higher than its single stage partner. In any case, it gives better output voltage direction, quick unique reaction and hinders the second symphonious (100Hz or 120Hz) segment in the main stage itself so that huge capacitors at the output side are avoided.

Different front end converters have been utilized in the power supplies for giving PFC and output voltage control. A lift converter is the basic decision for giving PFC in power supplies. Nonetheless, it is not the favored decision in PC control supplies because of its necessity for an expansive info voltage run [7]. The output voltage of a lift converter can't be controlled to an esteem under 300V for a 220V air conditioning input. Along these lines, a buck-support converter is favored in PCs where wide varieties in input voltages and load are normal [8-9]. Low output voltage swell is favored in a PC control supply as it is connected with different ICs. Single stage power supplies are utilized as a part of numerous applications where control quality change and voltage direction happen in a solitary stage. Be that as it may, in PCs, single stage

setup builds the worry over the switches and moderates the voltage direction under changing burdens. Consequently, two phase PFC air conditioning dc converters based SMPSs are being utilized to enhance the information control quality and furthermore to get an adequate output voltage direction. Be that as it may, the productivity of a two phase SMPS is lower than the ordinary SMPS. To wipe out this burden, another bridgeless front end converter is proposed in this paper for PC control supplies which offers low exchanging swell, sinusoidal information present and great dynamic reaction when contrasted with other non-disconnected buck-help converters. The end of DBR at the front final products in decreased conduction misfortunes and backings a bigger output voltage run with upgraded proficiency. At the output of the front end converter, a half scaffold converter is utilized which gives detachment, control and different dc outputs [18-20] with a superior center usage.

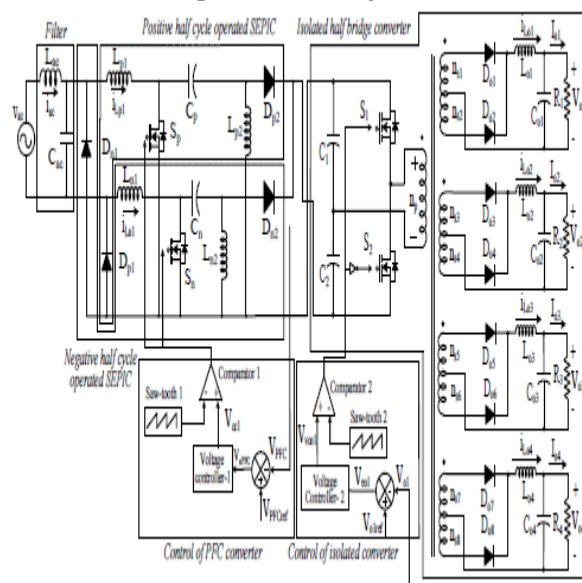
It is seen from the accessible writing that the power quality change in SMPSs utilizing bridgeless PFC converter has not been endeavored by numerous specialists up until this point. In this work, a bridgeless single finished essential inductance converter (SEPIC) working in broken conduction mode (DCM) is being utilized at the front end of the SMPS which offers magnificent PFC at the appraised and in addition light load condition. Upper converter works in the positive half cycle of the air conditioner voltage while the lower converter works in the negative half cycle. The output of the bridgeless PFC converter is connected with the detached converter. Test consequences of the proposed different output SMPS are found in accordance with the mimicked execution exhibiting its enhanced power quality and output voltage control.

## II. SMPS CONFIGUREURATION AND OPERATING PRINCIPLE

The proposed PC control supply comprises of chiefly two sections, bridgeless front end air conditioning dc converter and multi-output disconnected dc-dc converter. The working mode out of CCM (Continuous Conduction Mode) or DCM of the bridgeless front end converter might be chosen on the necessity of the client. A DCM is chosen if the cost is a noteworthy thought; if not, CCM is received that lessens gadget worries, regardless of the way that two voltage and one current sensor are required which makes it costlier.

Consequently, a DCM operation of the front end PFC converter is favored in PCs where just a single voltage sensor is required for detecting furthermore, control. Here, the front end converter is outlined in DCM for accomplishing inalienable PFC which requires just a single voltage sensor while the disengaged converter is composed in CCM.

The control circles of both converters are free of each other. The system design and working rule of SMPS system has been depicted in taking after subsections.



**Figure 1:** Schematic diagram of the PFC converter based SMPS

### A. System Configuration

The design of proposed power supply with four directed dc output voltages is appeared in Figure.1. At the info side, DBR is disposed of by utilizing two SEPICs. The upper converter works in the positive half cycle and the lower one work in the negative half cycle of the information air conditioning voltage. The exchanging frequency of both the converters is set at 20 kHz for effective control. The outline of output inductors for both the converters is completed in DCM to decrease the intricacy in control. The control of the output voltage can take care of wide varieties in the information voltage and the load. The output dc voltage ( $V_{PFC}$ ) is detected and contrasted and a reference voltage ( $V_{PFCref}$ ) from which the voltage mistake is acquired ( $V_{ePFC} = V_{PFCref} - V_{PFC}$ ) which is given to a corresponding furthermore, basic (PI) controller. The PI controller output ( $V_{cc1}$ ) is contrasted and a high frequency saw-tooth 1 wave to output PWM beats that are given to both switches all the while. In the

event that  $St < V_{cc1}$  and  $V_{ac}$  is certain, at that point  $Sp$  is on, else  $Sp$  stays off.  $St$  speaks to the exchanging signals for the bridgeless air conditioning dc converter. The width of these PWM beats shifts as indicated by the output of the PI voltage controller-1 so that the output dc voltage  $VPFC$  is directed adequately which is, thusly, nourished to the disconnected half extension converter in the second stage to acquire different secluded directed output voltages. Thus, the width of PWM heartbeats changes as needs be to keep up dc output voltage  $VPFC$  steady. The seclusion is affected through multi winding high frequency transformer (HFT). An inside tapped arrangement is picked at the output side to decrease the conduction misfortunes. All the optional windings are controlled through one control circle. The most elevated appraised optional twisting of the HFT is chosen for voltage detecting. The distinction between the output voltage ( $Vo1$ ) and reference voltage ( $Vo1ref$ ) is encouraged to another PI voltage controller-2 which output is contrasted and another high frequency saw-tooth wave 2 to create second arrangement of PWM signs for the half-connect converter gadgets  $S1$  and  $S2$ . Care ought to be taken to make beyond any doubt that there is adequate dead-time between killing of  $S1$  and turn-ON of  $S2$  to maintain a strategic distance from shoot-through blame. The confined converter is worked in CCM to take the upside of decreased stretch. In the event that the load in any of the winding changes, the obligation cycle changes in like manner to guarantee managed dc voltage outputs. The reaction of alternate outputs is slower than the one where the output voltage is detected.

**B. Operating Principle**

The operation of the front end converters and the isolated converter are described independently as follows:

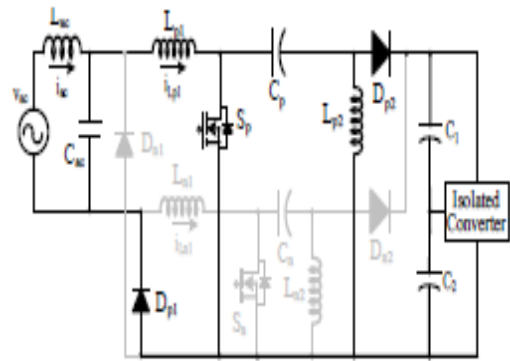
**1) Operating principle of front end converter**

Amid the positive half cycle of the information voltage, the upper SEPIC works as appeared in Figure. 2. Similarly, amid negative half cycle the lower SEPIC would work. The operation of the SEPIC in one PWM cycle is portrayed with the assistance of the accompanying modes: In the

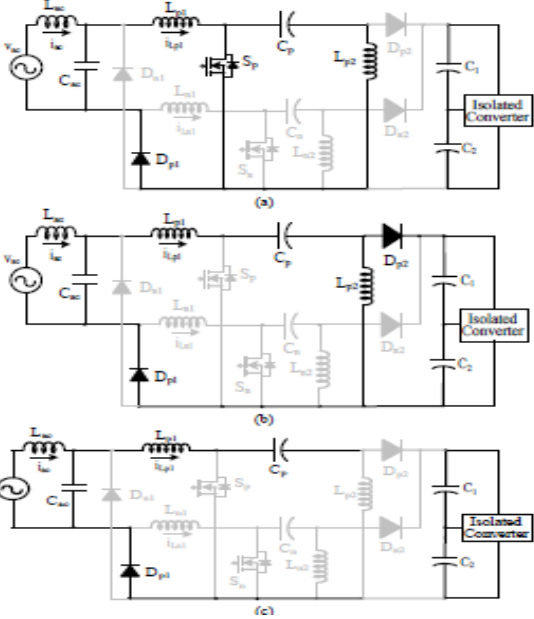
primary mode, the high frequency switch  $Sp$  turns on, the information inductor  $Lp1$  begins putting away the vitality which is exchanged from the single stage air conditioning mains as appeared in Figure. 3a. Diode  $Dp1$  finishes the present way. In the second mode,  $Sp$  is killed and diode  $Dp2$  begins directing. The vitality in output inductor  $Lp2$  begins diminishing to zero which is appeared in Figure. 3b. In the last exchanging state, the current in the output inductor stays zero until the begin of next exchanging cycle. This mode guarantees the DCM operation as appeared in Figure. 3c.

**2) Operating principle of isolated converter**

Two high frequency switches are turned on and off on the other hand in one exchanging cycle. In this way, the operation of the converter in one portion of the exchanging cycle is the same as that of the other half cycle. In the primary half cycle, the upper switch  $S1$  is turned on. The diodes on the auxiliary side ( $Do1, Do3, Do5$  and  $Do7$ ) begin directing and the inductors ( $Lo1-$



**Figure 2:** Operation of PFC converter when the input voltage is positive



**Figure 3:** Operating modes of bridgeless PFC converter when the input voltage is positive

Lo4) in all the optional windings begin putting away vitality. At the point when the inductor current achieves its most extreme esteem, upper turn S1 is killed. All the channel capacitors release through the loads to keep up dc output voltages as consistent. In the following half cycle of the PWM period, the upper turn is killed. The auxiliary diodes (Do1-Do8) are swung on to free-wheel the inductors streams. The current in every single auxiliary winding scratch off center flux so that net voltage crosswise over HFT ends up noticeably zero. A similar inductor charging and releasing happen in next half exchanging cycle with the lower switch S2.

### III. DESIGN OF PROPOSED BRIDGELESS CONVERTER BASED SMPS SYSTEM

The design of proposed bridgeless converter based SMPS is described in the following section.

#### A. Design of Proposed SMPS System

The design for the positive half cycle operated PFC converter is carried out here. The negative half cycle operated converter is designed in the same way. The average voltage  $V_{acav}$  is calculated as,

$$V_{acav} = \frac{2\sqrt{2}V_{ac}}{\pi} = \frac{2\sqrt{2} \times 220V}{3.14} = 198V \quad (1)$$

The duty cycle  $D$  of the PFC buck-boost converter is expressed as the ratio of its output dc voltage to the sum of output dc voltage and input voltage.

$$D = \frac{V_{PFC}}{V_{PFC} + V_{acav}} = \frac{300V}{300V + 198V} = 0.6 \quad (2)$$

Irrespective of variation in the input voltage from 170V to 270V, the output voltage is maintained constant at 300V. Hence, the duty cycles for supply voltages of 170V voltage, 220V and 270V are calculated as,  $D_{170V}=0.66$ ,  $D_{220V}=0.6$ ,  $D_{270V}=0.552$  respectively. The duty cycle  $D$  of the PFC converter is taken less than  $D_{220V}$  for an efficient control during DCM operation. Therefore, it is considered as 0.25 for the design of the PFC converter.

The input inductor value is calculated for the permitted ripple of 40% of input current.

$$L_{p1} = \frac{DV_{acav}}{f \times (i_{inripple})} = \frac{0.25 \times 198V}{20kHz \times 0.58A} = 4.35mH \quad (3)$$

Where,  $f$  is the switching frequency of the PFC converter. The critical conduction parameter is given as,

$$K_c < \frac{1}{2 \left( \frac{V_{PFC}}{\sqrt{2}V_{ac}} + n \right)^2} = \frac{1}{2 \left( \frac{300V}{311V} + 1 \right)^2} = 0.129 \quad (4)$$

Where,  $n$  is taken as 1 for the non-isolated PFC converter. To operate the PFC converter in DCM, the conduction parameter should be taken less than  $K_a$  for efficient control. Hence, it is selected as 0.08.

The equivalent value of inductance of the PFC converter is given as,,

$$L_{eq} = \frac{R_s K_c}{2f} = \frac{281.2\Omega \times 0.08}{2 \times 20kHz} = 225\mu H \quad (5)$$

Therefore, the output inductor value is calculated as,

$$L_{p2} = \frac{L_{p1} L_{eq}}{L_{p1} - L_{eq}} = \frac{4.31mH \times 225\mu H}{4.31mH - 225\mu H} = 237\mu H \quad (6)$$

The selected value of output inductor is 100  $\mu H$  to ensure DCM condition in all operating conditions of input voltages, load and unity PF operation at a low input voltage.

The intermediate capacitor value is estimated as,

$$C_p = \frac{1}{\omega_r (L_{p1} + L_{p2})} = \frac{1}{2 \times \pi \times 2000Hz (4.3mH + 0.1mH)} = 0.18\mu F \quad (7)$$

where,  $\omega_r$  is the angular frequency ( $\omega_r = 2\pi fr$ ). A  $fr$  is considered as 2000Hz ( $f > fr > fL$ ). A capacitor value of 0.22 $\mu F$  is selected for the hardware implementation.

An L-C filter is used at the input side to mitigate higher order harmonics. The maximum value of the capacitor is as,

$$C_{ac} = \frac{I_p \tan \theta}{\omega V_c} = \frac{2.25A \times 0.017}{314 \times 311V} = 391nF \quad (8)$$

The filter capacitor value is selected such that it is less than  $C_{ac}$ . Hence, a 330nF capacitor is selected in hardware implementation.

The filter inductor  $L_{ac}$  is calculated for mitigating high order harmonics close to 5 kHz frequency.

$$L_{ac} = \frac{1}{4\pi^2 f_c^2 C_d} = \frac{1}{4 \times (3.14 \times 5 \times 10^3)^2 \times 330 \times 10^{-9}} = 3.07mH \quad (9)$$

A 3.1mH inductor is selected for simulation and experimental system.

The input capacitors of the isolated half bridge dc-dc converter act as the output filter capacitors for the PFC converter. So, the design of the capacitor is important to eliminate the second order harmonic component as well as to provide maximum power for that duration when input voltage falls. This is very crucial for PC power supplies as the rating of the capacitor affects the size and the cost of the overall SMPS.

The expression for calculating the capacitor to reduce second order harmonic is as,

$$\frac{C_1}{2} = \frac{C_2}{2} = \frac{I_{PFC}}{2\omega\Delta V_{PFC}} = \frac{1.06A}{2 \times 314 \times 6V} = 0.28mF \quad (10)$$

The hold-up capability can be estimated as,

$$t_{hold-up} = (V_{PFCm}^2 - V_{PFCmin}^2) \frac{C}{2P_o} \quad (11)$$

where, thold-up is the holdup time of the capacitor, Po is the maximum output power, V<sub>PFC m</sub> is the minimum output voltage (2% ripple is considered) and V<sub>PFC min</sub> is the minimum voltage at which the output voltage holds regulation.

Therefore, to maintain 10ms hold-up time, the required capacitance is calculated as,

$$C = \frac{2t_{hold-up}P_o}{(V_{PFCm}^2 - V_{PFCmin}^2)} = \frac{2 \times 10ms \times 320W}{(294V)^2 - (260V)^2} = 0.339mF \quad (12)$$

Two capacitors are connected in series. Therefore, the value of C1=C2=0.679 mF. The selected value of the capacitors is 0.6mF each to meet both the conditions.

The calculation of inductance for the secondary winding with highest rating is shown here, while the calculation for rest of the secondary windings remains same. The inductance Lo1 is expressed as,

$$L_{o1} = \frac{V_{o1}(0.5 - D_s)}{f_s \Delta i_{L_{o1}}} = \frac{12V(0.5 - 0.4)}{60kHz \times 0.625A} = 0.032mH \quad (13)$$

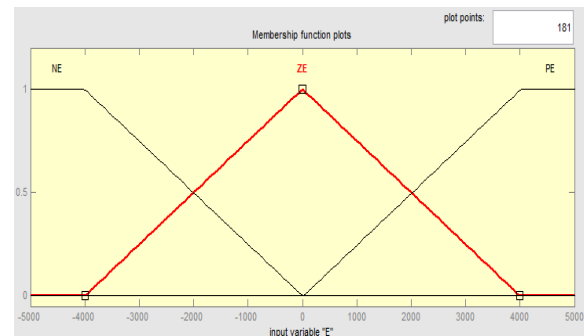
Similarly, the inductances for the other secondary windings are calculated as 9.5 μH, 6.8 μH and 1.5 mH.

## Extension

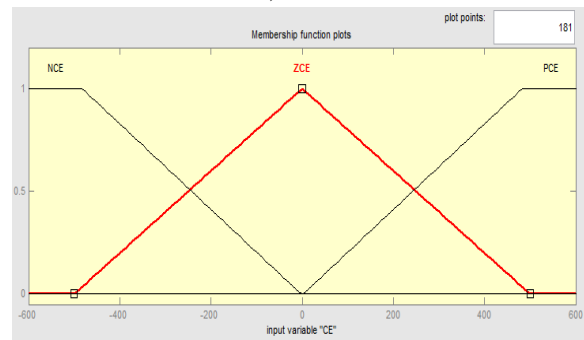
### Fuzzy Logic Controller

Fuzzy logic is a complex mathematical method that allows solving difficult simulated problems with many inputs and output variables. Fuzzy logic is able to give results in the form of recommendation for a specific interval of output state, so it is essential that this mathematical method is strictly distinguished from the more familiar logics, such as Boolean algebra.

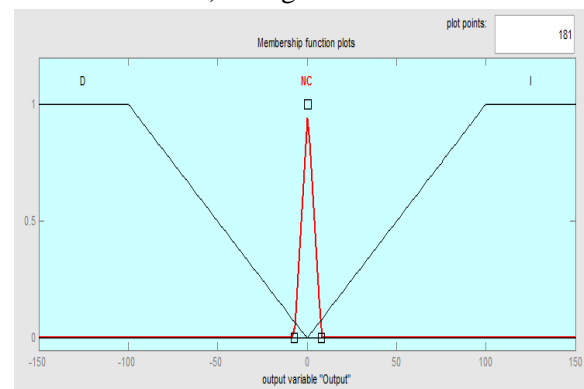
### Membership Functions



a)Error



b)Change in error



c)Output

### Advantages of Fuzzy Controller over PI Controller

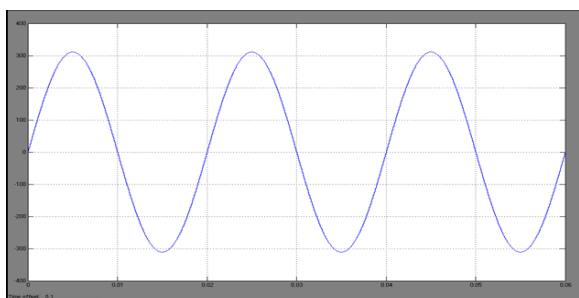
Usage of conventional control "PI", its reaction is not all that great for non-linear systems. The change is striking when controls with Fuzzy logic are utilized, acquiring a superior dynamic reaction from the system.

Or

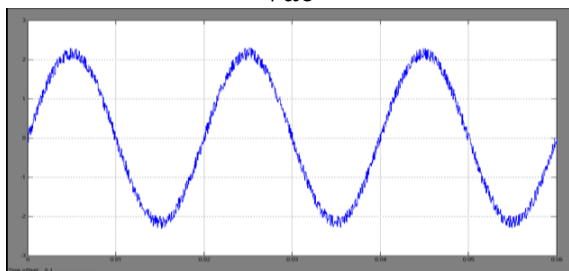
The PI controller requires exact direct numerical models, which are hard to get and may not give tasteful

execution under parameter varieties, load unsettling powers, and so forth. As of late, Fuzzy Logic Controllers (FLCs) have been presented in different applications and have been utilized as a part of the power devices field. The benefits of fuzzy logic controllers over ordinary PI controllers are that they needn't bother with a precise scientific model, Can work with uncertain information sources and can deal with non-linearities and are more dynamic than traditional PI controllers.

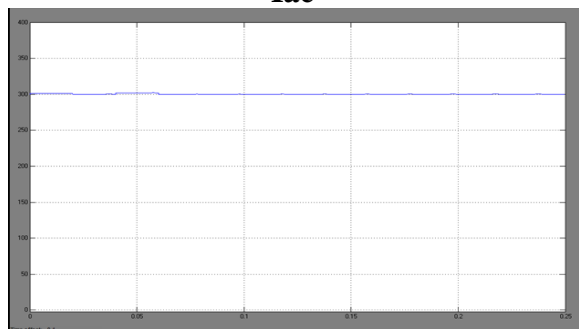
**Case1 : Full Load condition**



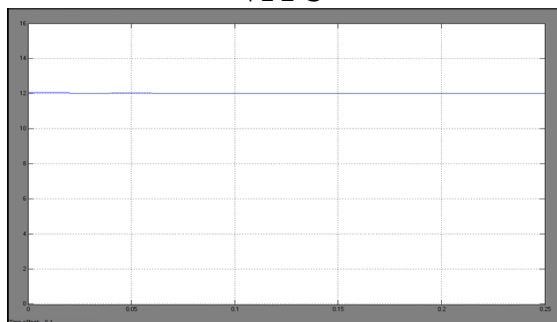
**Vac**



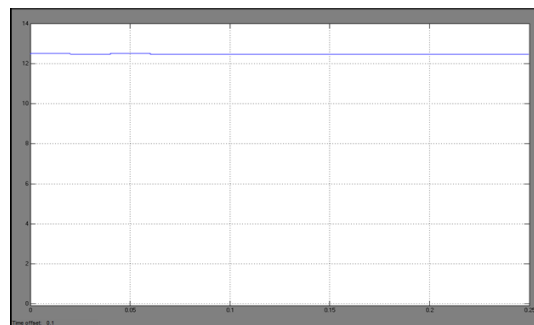
**Iac**



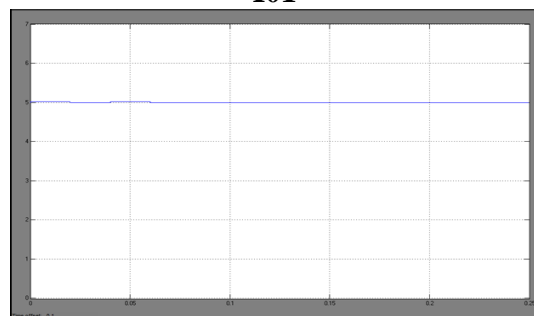
**VPFC**



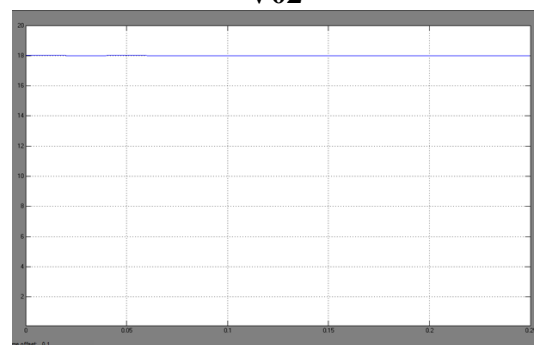
**V01**



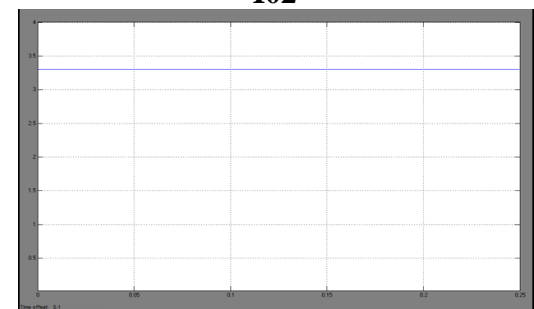
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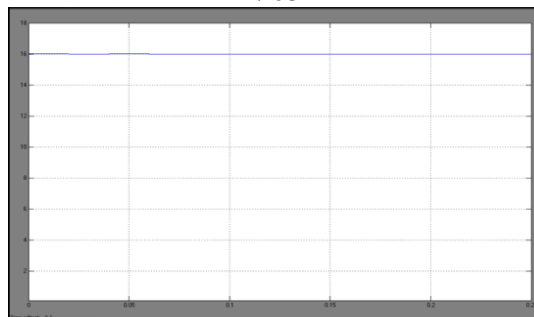
**V02**



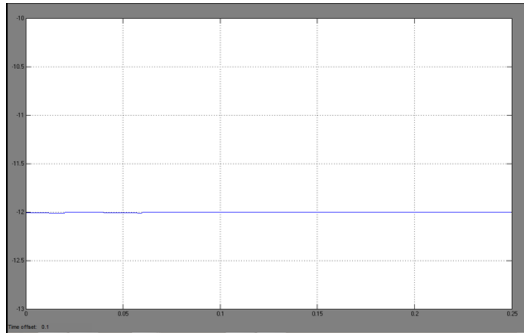
**I02**



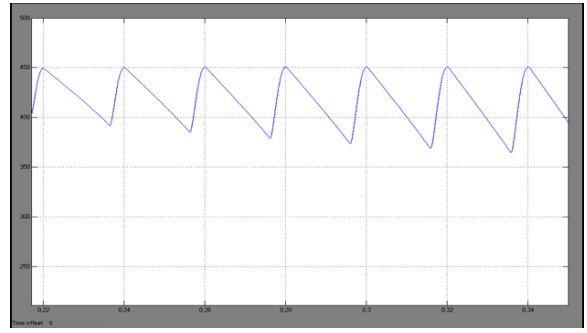
**V03**



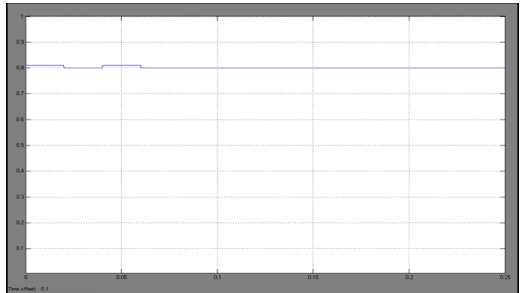
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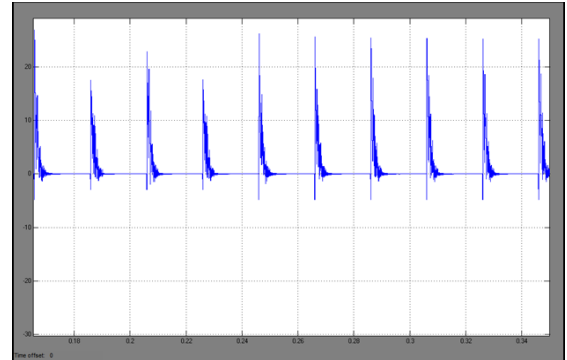
**V04**



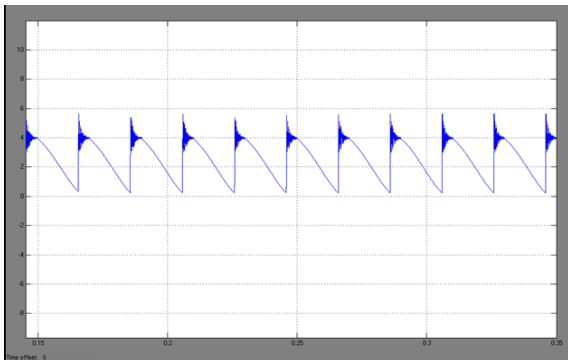
**Vcn**



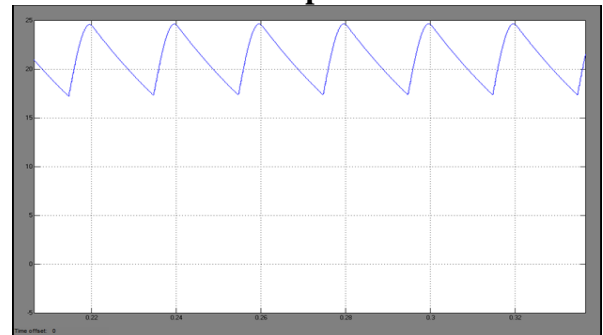
**I04**



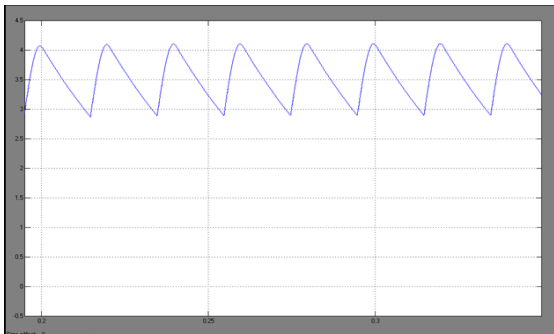
**ILp2**



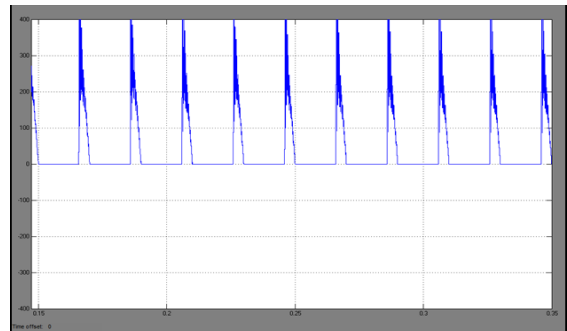
**ILP1**



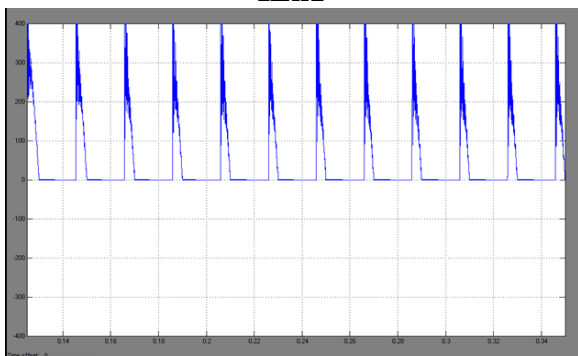
**ILn2**



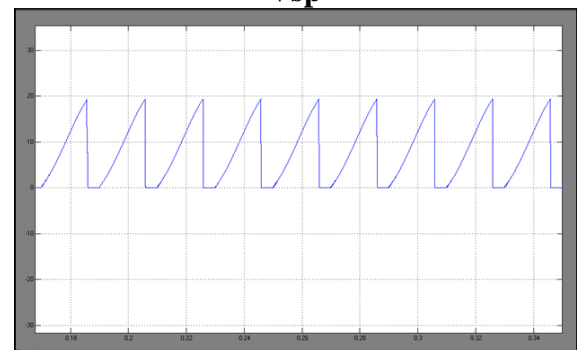
**ILn1**



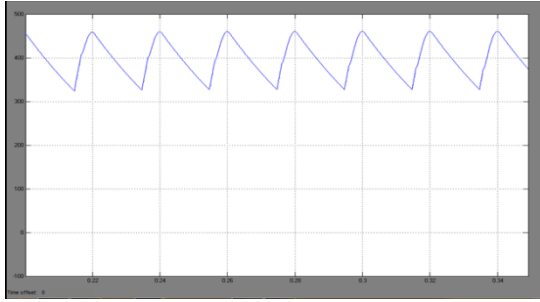
**Vsp**



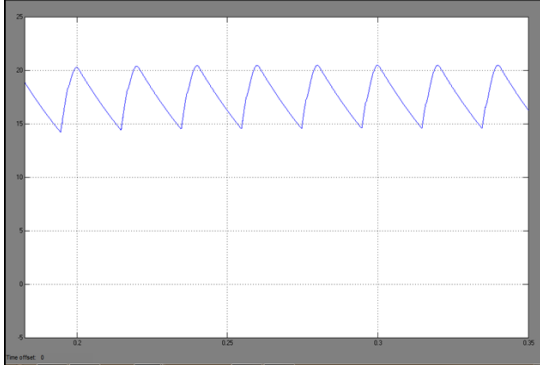
**Vcp**



**Isp**

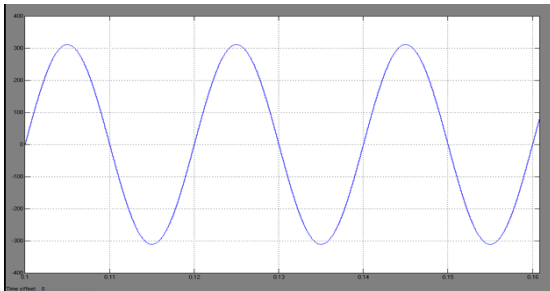


**Vsn**

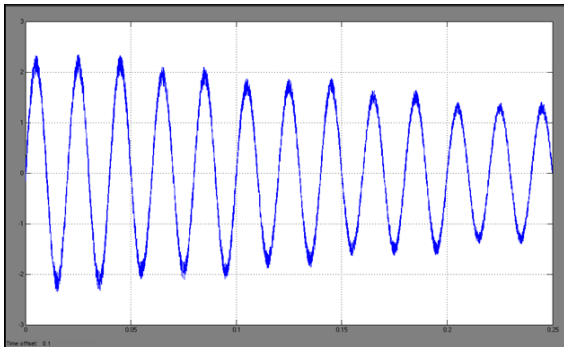


**Isn**

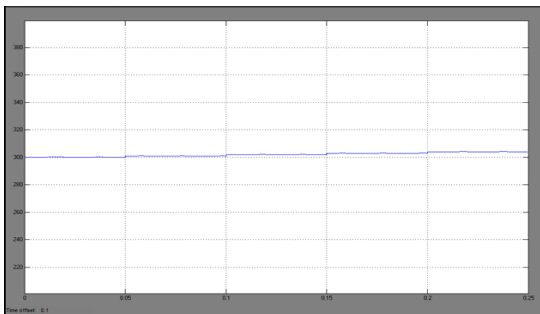
**Case2: Load Changing Condition**



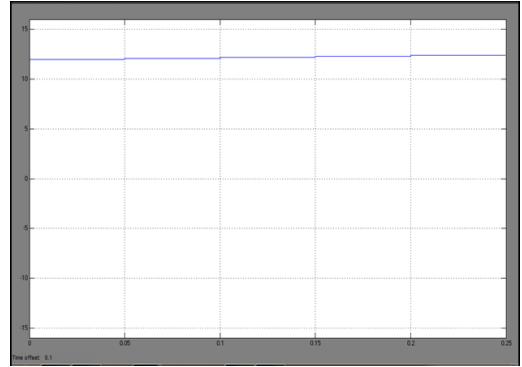
**Vac**



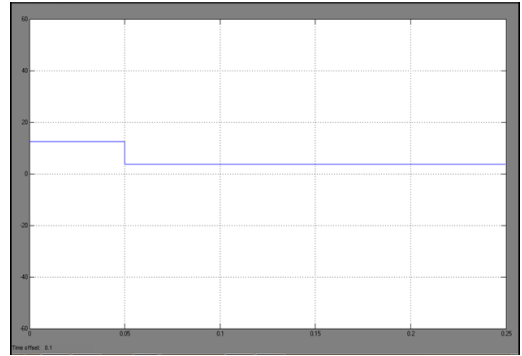
**Iac**



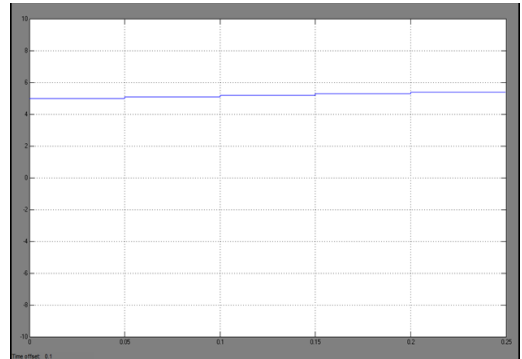
**Vpfc**



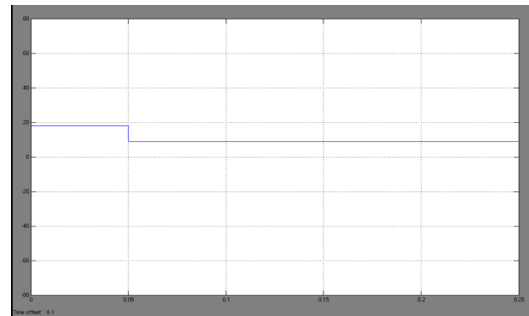
**V01**



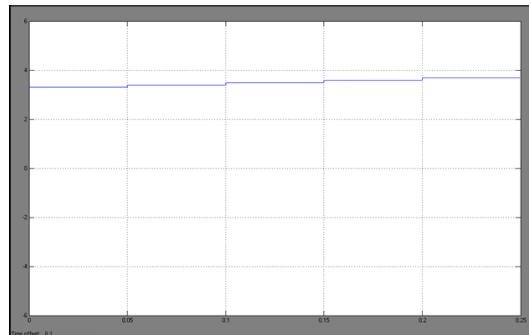
**I01**



**V02**

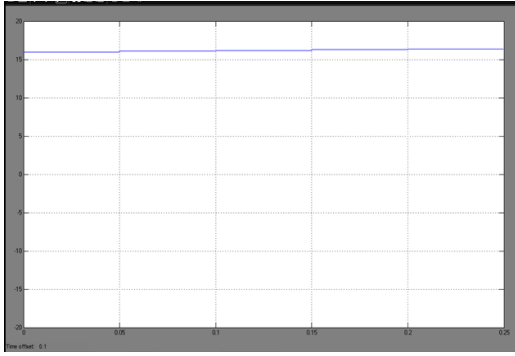


**I02**

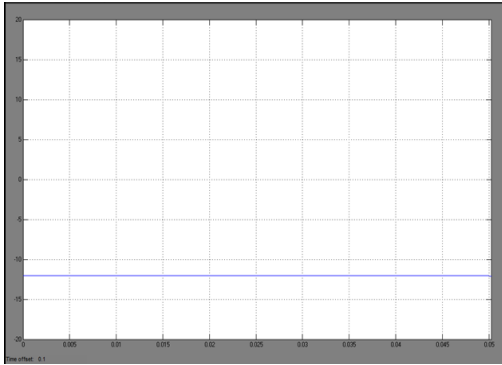


**V03**

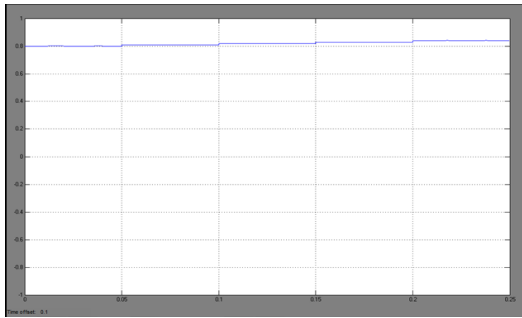




**I03**

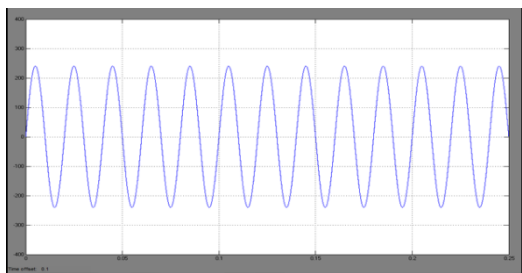


**V04**

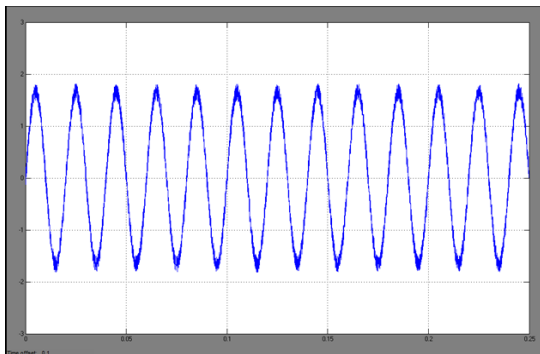


**I04**

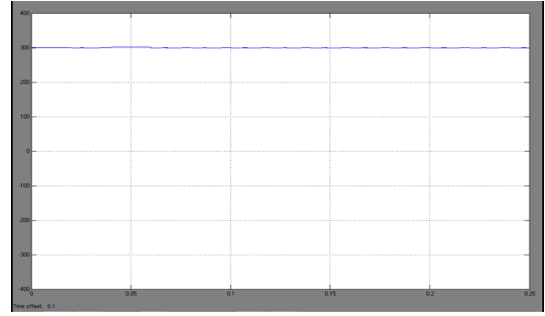
**Case3: Supply Voltage\_170v**



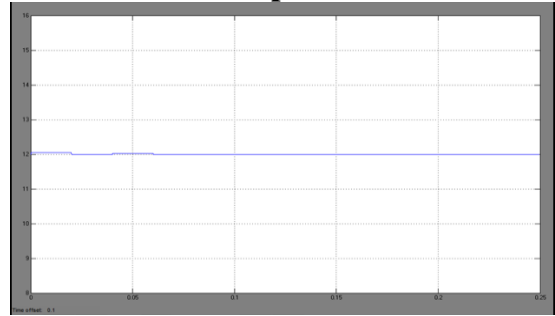
**Vac**



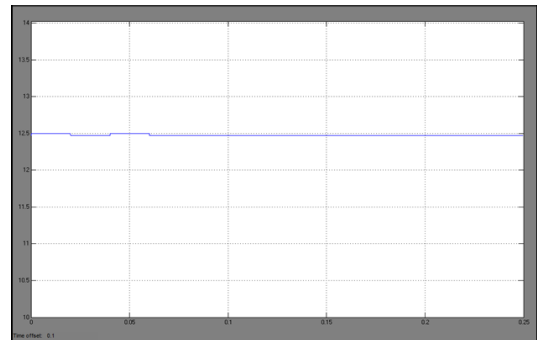
**Iac**



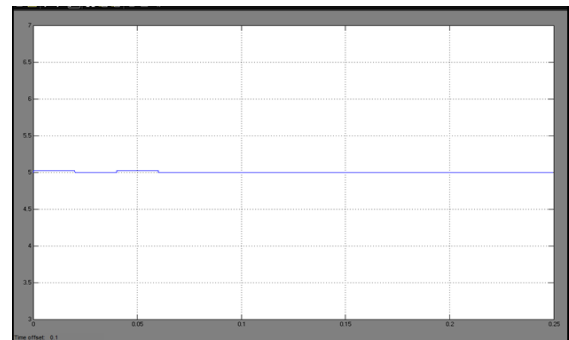
**Vpfc**



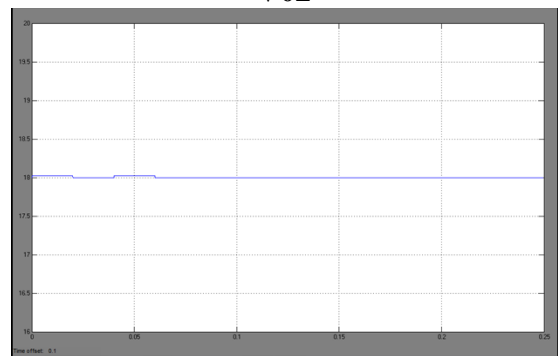
**V01**



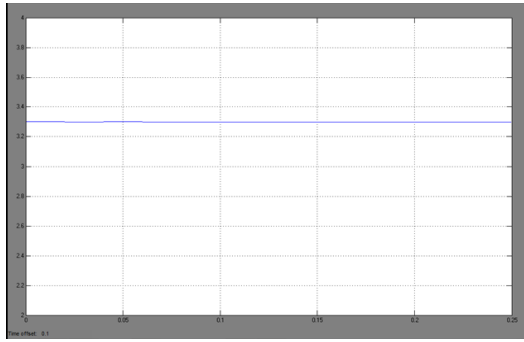
**I01**



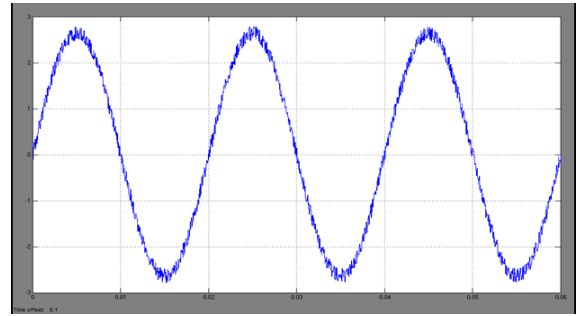
**V02**



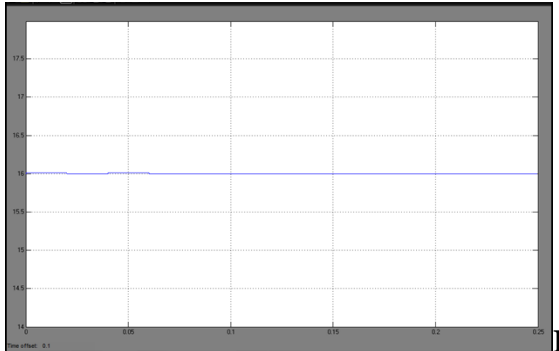
**I02**



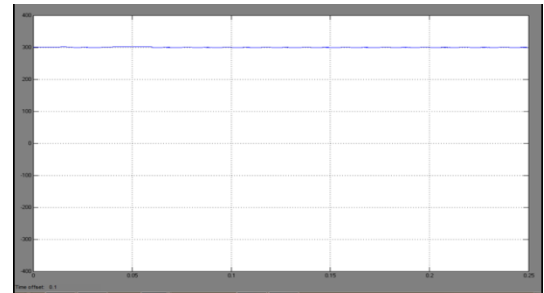
**V03**



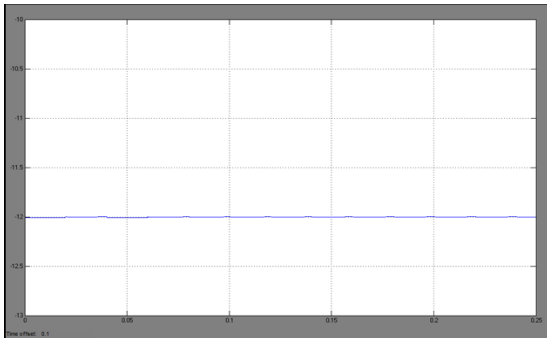
**Iac**



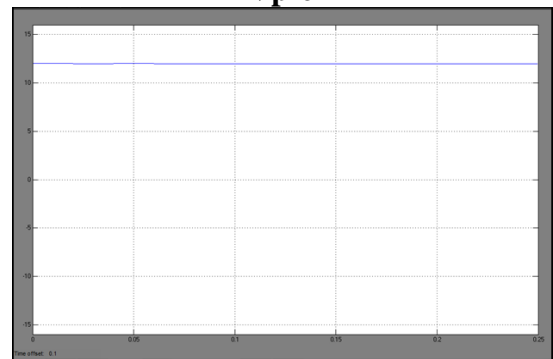
**I03**



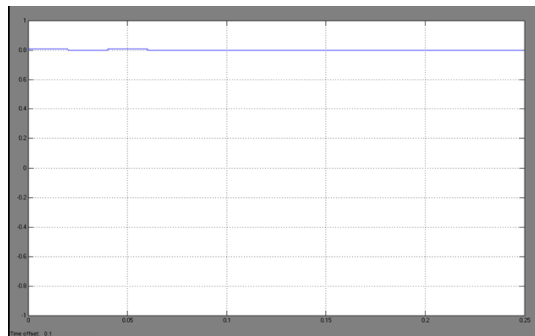
**Vpfc**



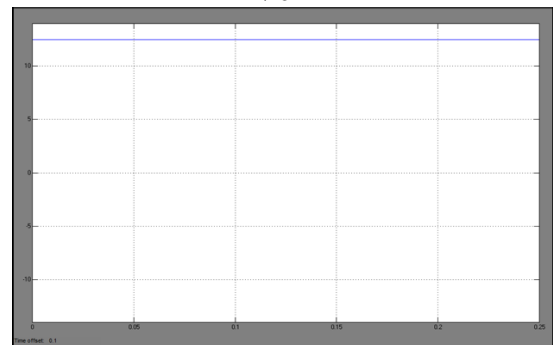
**V04**



**V01**

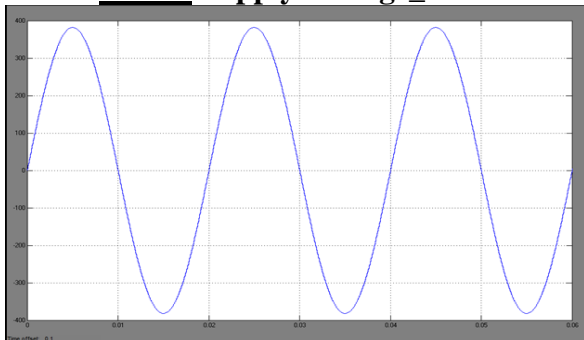


**I04**

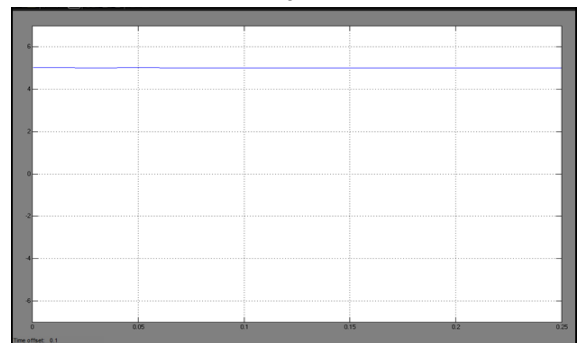


**I01**

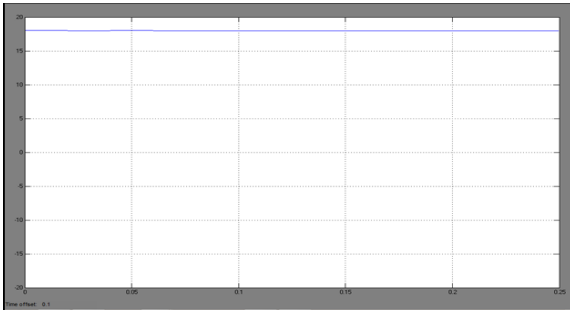
**Case4: Supply Voltage\_270v**



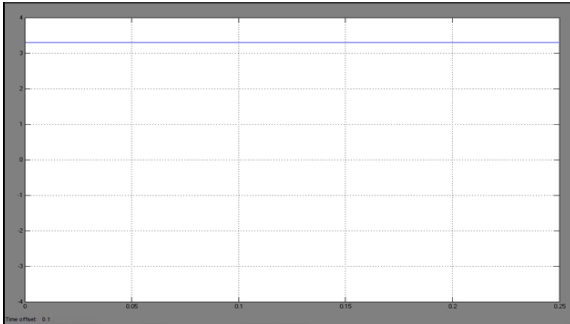
**Vac**



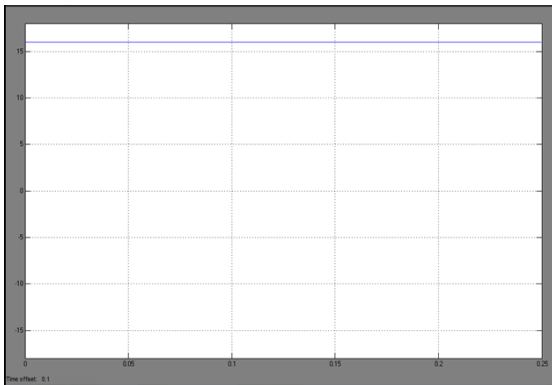
**V02**



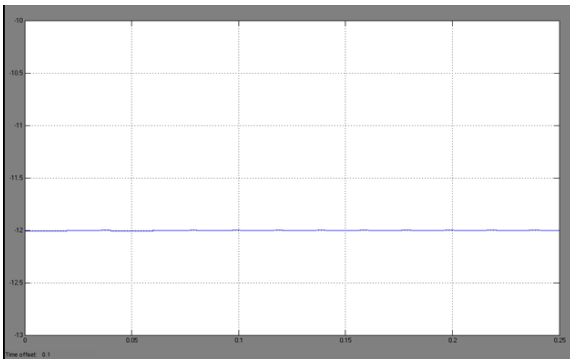
**I02**



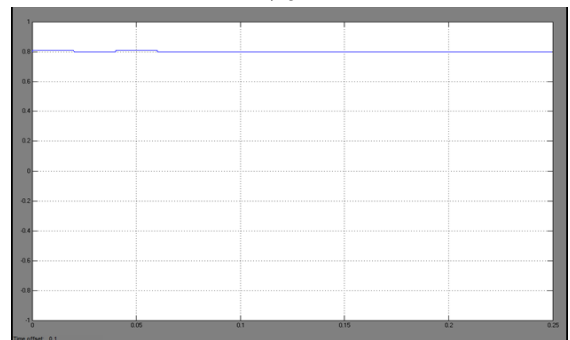
**V03**



**I03**



**V04**



**I04**

**TABLE I**

	<b>Proposed</b>	<b>Extension</b>
Full load $I_{ac}$	3.33	2.76
Load changing $I_{ac}$	3.76	2.84
Full load condition 170v $I_{ac}$	4.30	3.30
Full load condition 270v $I_{ac}$	2.71	2.08

## VI. CONCLUSION

A bridgeless non-separated SEPIC based power supply has been proposed here to alleviate the power quality issues unavoidable in any normal PC control supply. The proposed control supply can work elegantly under wide assortments in data voltages and weights. The layout and entertainment of the proposed control supply are at first passed on to show its improved execution. Further, an exploration focus display is developed and examinations are coordinated on this model. Test comes to fruition gained are seen to be as per the reproduced execution. They affirm the way that the power quality issues at the front end are eased and accordingly, the proposed circuit can be a recommended respond in due order regarding PCs and other near machines.

## V. REFERENCES

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